### CSE 6363 - Machine Learning

Probability Theory

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### What is probability theory?

A consistent framework for the quantification and manipulation of **uncertainty**.

We will cover some probabilistic methods for machine learning in this course.

A brief review of probability theory and some fundamental distributions wouldn't hurt!

Let's start with an example...

There are two cookie jars

- A blue jar with 8 oatmeal raisin cookies
- A red jar with 10 chocolate chip cookies

### However, some monsters took 2 chocolate chip cookies and put them in the blue jar

and placed 1 oatmeal raisin cookie in the red jar.

#### The blue jar now has 2 chocolate chip and 7 oatmeal raisin.

The red jar has 8 chocolate chip and 1 oatmeal raisin.

Let's further say that we happen to pick the red jar 80% of the time and the blue jar 20% of the time.

We can start to formulate about these events via probability by assigning these actions to **random variables**.

We have two types of things: cookies and jars. Let's assign them to variables.

- J The type of jar, either blue b or red r.
- C The type of cookie, either oatmeal o or chocolate chip c.

We can present the probabilities of picking each type of jar using a functional notation:

- p(J = b) = 0.2
- p(J = r) = 0.8

Notice that their sum is 1. This makes sense considering they are the only 2 jars in our problem.

We can also define the probability of picking each cookie.

- p(C = o)
- p(C = c)

However, this probability is based on which jar is picked.

We can also define the probability of picking each cookie.

	Chocolate Chip	Oatmeal Raisin
Blue Jar	$\frac{2}{9} = 0.222$	$\frac{7}{9} = 0.778$
Red Jar	$\frac{8}{9} = 0.889$	$\frac{1}{9} = 0.111$

Given these quantities, we can ask slightly more complication questions.

## What is the probability that I will select the red jar AND take a chocolate chip cookie?

This is expressed as a **joint probability distribution**, p(J = r, C = c).

p(J = r, C = c) is defined based on

- the prior probability of picking the red jar,
- the conditional probability of picking the chocolate chip cookie **conditioned** on the red jar being picked.

Mathematically, p(J = j, C = c) = p(C = c|J = r)p(J = r).

$$p(J = j, C = c) = p(C = c|J = r)p(J = r)$$

is also known as the **product rule**.

We have all of the quantities we need to answer this.

Thus,

$$p(J = r, C = c) = 0.8 * 0.889 = 0.711$$

If we knew nothing about the contents of the jar or the prior probabilities of selecting a specific jar, we could measure this probability empirically.

### Conduct *N* trials of taking a cookie from one of the jars, recording it, and placing it back in the same jar.

Count the number of times we select a red jar AND a chocolate chip cookie.

### If we wanted to measure the **conditional probability** p(C = c|J = r)...

Count the number of times a chocolate chip cookie is taken (and replaced) from the red jar and divide by *N*.

#### Calculating all joint probabilities produces a joint probability table:

	Chocolate Chip	Oatmeal Raisin
Red Jar	0.711	0.089
Blue Jar	0.044	0.156

Note that the sum of the sum of rows is equal to 1.

Likewise, the sum of the sum of columns is equal to 1.

The sum of the each column for a given row adds up to the prior probability of selecting a jar.

The sum of each row for a given column is the prior probability of selecting a cookie.

These are called marginal probabilities.

### In general, the marginal probability can be computed by summing out the joint variables:

$$p(x_i) = \sum_j p(x_i, y_j)$$

### What if we want the joint probability over *k* variables?

 $p(a_1, \cdots, a_k)$ 

### What if we want the joint probability over *k* variables?

$$p(a_1,\cdots,a_k)=p(a_1)p(a_2|a_1)\cdots p(a_k|a_1,\cdots,a_{k-1})$$

Notationally, p(X, Y) and p(Y, X) would be written slightly differently, but they are equal.

Setting them equal to each other is the basis of the derivation of **Bayes'** rule:

$$p(X, Y) = p(Y, X)$$
$$p(X|Y)p(Y) = p(Y|X)p(X)$$
$$p(X|Y) = \frac{p(Y|X)p(X)}{p(Y)}$$

$$p(X|Y) = \frac{p(Y|X)p(X)}{p(Y)}$$

This will come in handy in for many probabilistic methods later on.

# In the context of Bayes' rule, p(X|Y) is referred to as the **posterior probability** of event *X* conditioned on the fact that we know event *Y* has occurred.

p(X) is the **prior probability** of event X in the absence of any additional evidence.

Murphy presents an excellent example of understanding probabilities via Bayes' rule.

- *H* is the infected state (1 for yes, 0 for no)
- Y is the test event (1 for positive, 0 for negative)

We want to find p(H = h|Y = y): the probability of the state of infection given a test result.

### The **sensitivity** is p(Y = 1|H = 1).

The probability of testing positive conditioned on actually being infected.

### The false negative rate is 1 - p(Y = 1|H = 1).

Also written as p(Y = 0|H = 1).

The **specificity** is defined as p(Y = 0|H = 0).

The probability of testing negative conditioned on no infection.

The false positive rate is defined as p(Y = 1|H = 0).

The probability of testing positive conditioned on no infection.

Also defined as 1 - p(Y = 0|H = 0).

#### Now that we have defined the likelihoods, we need the priors.

The **prevalence** of the disease in your area is p(H = 1).

Let's apply some values to these quantities. Suppose the likelihoods follow the table below.

	Y = 0	Y = 1
H = 0	0.975	0.025
H = 1	0.125	0.875

Additionally, we'll suppose the prevalence of infection p(H = 1) = 0.05.

If you test positive, what is the probability that you are actually infected (true positive rate)?

$$p(H = 1|Y = 1) = \frac{p(Y = 1|H = 1)p(H = 1)}{\sum_{h} p(Y = 1|H = h)p(H = h)}$$
$$= \frac{0.875 \times 0.05}{0.875 \times 0.05 + 0.025 \times 0.95}$$
$$= 0.648$$

There is a 64.8% chance you are infected.

### If you test negative, what is the probability that you are actually infected?

Using the same data, we can calculate p(H = 0|Y = 1) = .0067, or 0.67%.

Two variables are **independent**, then

p(X,Y) = p(X)p(Y)

If two variables are conditionally independent given a third event, then

p(X, Y|Z) = P(X|Z)P(Y|Z)

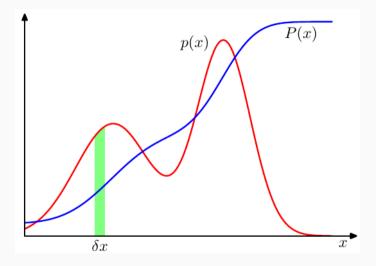
#### In the introductory example, the events took on discrete values.

Most of the problems we will see in this course involve **continuous values**.

#### Consider a small differential of a random variable x, $\delta x$ .

The probability density is p(x).

### Continuous Variables



**Figure 1:** PDF p(x) and CDF P(x). Source: Bishop

### With the small differential $\delta x$ , the probability that x lies on some interval (a, b) is given by

$$p(a \le x \le b) = \int_a^b p(x) dx$$

The probability density must sum to 1 and cannot take a negative value.

$$p(x) \ge 0$$
$$\int_{-\infty}^{\infty} p(x) dx = 1$$

However, it is possible to have a value greater than 1 as long as the integrals over any interval are  $\leq 1$ .

## The cumulative distribution function P(x) is the probability that x lies in the interval $(-\infty, z)$

$$\mathsf{P}(z) = \int_{\infty}^{z} p(x) dx.$$

Note that the derivative of the cdf is equal to the pdf.

## The **product rule** for continuous probability distributions takes on the same form as that of discrete distributions.

The **sum rule** is written in terms of integration:

$$p(x) = \int p(x, y) dy$$

A **moment** of a function describes a quantitative measurement related to its graph.

With respect to probability densities, the *k*th moment of p(x) is defined as  $\mathbb{E}[x^k]$ .

The first moment is the **mean** of the distribution, the second moment is the **variance**, and the third moment is the **skewness**.

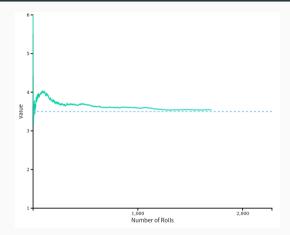
# The **expectation** of a function is the mean under a proability distribution p(x)

$$\mathbb{E}[f] = \sum_{x} p(x)f(x) \text{ and}$$
$$\mathbb{E}[f] = \int p(x)f(x)dx,$$

Given a fair d6, for which each value is equally likely,  $p(x) = \frac{1}{6}$ , the expectation is

$$\mathbb{E}[f] = \sum_{x} p(x)f(x)$$
  
=  $\frac{1}{6}(1+2+3+4+5+6)$   
= 3.5

### Expectation



**Figure 2:** Expectation of rolling a d6 over 1800 trials converges to 3.5. Source: Seeing Theory

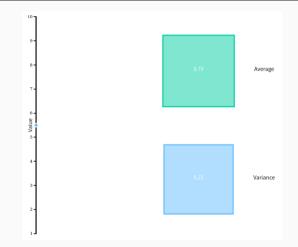
# The **variance** of a function f(x) under a probability distribution p(x) measures how much variability is in f(x) around the expected value $\mathbb{E}[f(x)]$

$$\operatorname{var}[f] = \mathbb{E}[(f(x) - \mathbb{E}[f(x)])^2]$$
$$= \mathbb{E}[f(x)^2] - \mathbb{E}[f(x)]^2.$$

### If we have a stack of 10 cards with values 1-10 and draw 1 (with replacement) over *N* trials, the variance is

$$var[f] = \mathbb{E}[f(x)^{2}] - \mathbb{E}[f(x)]^{2}$$
  
= 38.5 - 30.25  
= 8.25

### Variance



**Figure 3:** Variance of drawing a card (1-10) over *N* trials converges to 8.25. Source: Seeing Theory

The **covariance** of two random variables *x* and *y* provides a measure of dependence between them.

$$cov[\mathbf{x}, \mathbf{y}] = E_{\mathbf{x}, \mathbf{y}}[\{\mathbf{x} - \mathbb{E}[\mathbf{x}]\}\{\mathbf{y}^{\mathsf{T}} - \mathbb{E}[\mathbf{y}^{\mathsf{T}}]\}]$$
$$= \mathbb{E}_{\mathbf{x}, \mathbf{y}}[\mathbf{x}\mathbf{y}^{\mathsf{T}}] - \mathbb{E}[\mathbf{x}]\mathbb{E}[\mathbf{y}^{\mathsf{T}}].$$

### Covariance

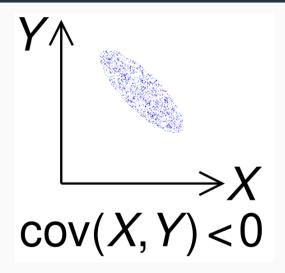
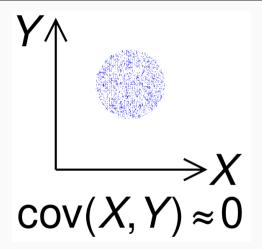


Figure 4: Plot of variables for with the covariance is negative. Source: Wikipedia

### Covariance



**Figure 5:** Plot of variables for with the covariance is approximately 0. Source: Wikipedia

### Covariance

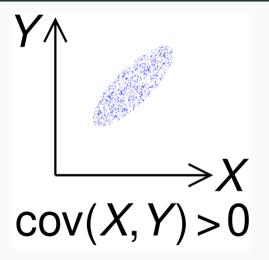


Figure 6: Plot of variables for with the covariance is positive. Source: Wikipedia 55

### The **correlation** between two random variables *x* and *y* relates to their covariance, but it is normalized to lie between -1 and 1.

$$corr[\mathbf{x}, \mathbf{y}] = \frac{cov[\mathbf{x}, \mathbf{y}]}{\sqrt{var[\mathbf{x}]var[\mathbf{y}]}}$$

The correlation between two variables will equal 1 if there is a linear relationship between them.

We can then view the correlation as providing a measurement of linearity.

### Correlation

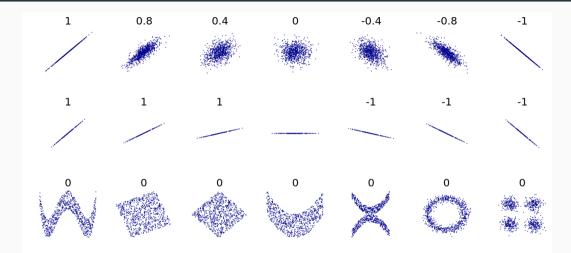


Figure 7: Sets of points with their correlation coefficients. Source: Wikipedia

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When possible, it is always better to visualize the data.

An example of this is the **Anscombosaurus**, derived from the Anscombe's quartet.

The quartet consists of four datasets that have nearly identical summary statistics but are visually distinct.

A modern version, called the Datasaurus Dozen, consists of 12 datasets that have the same summary statistics but are visually distinct.

#### Anscombosaurus

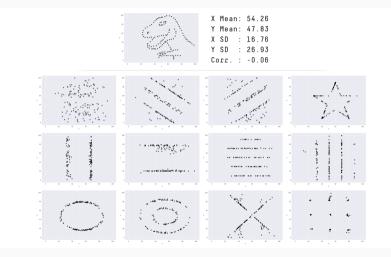


Figure 8: The Anscombosaurus. Source: Datasaurus Dozen